Craig A. Woolsey

https://www.aoe.vt.edu/people/faculty/woolsey.html

Contact Information:

Virginia Tech, Aerospace & Ocean Engineering Nonlinear Systems Laboratory 1991 Kraft Dr, Suite 2008 Blacksburg, VA 24060

E-mail: <u>cwoolsey@vt.edu</u>

Research Interests:

Dr. Woolsey's research interests include nonlinear control theory for mechanical systems, particularly energy-based control methods, and applications to ocean and atmospheric vehicles. Woolsey directs the Nonlinear Systems Lab (www.nsl.aoe.vt.edu), with co-directors Dr. Mazen Farhood and Dr. Cornel Sultan. Woolsey is also co-director, with Dr. Ella Atkins and Dr. Kevin Kochersberger (Director), of the Virginia Tech site in the Center for Autonomous Air Mobility and Sensing (ceams.center), an NSF Industry/University Cooperative Research Center.

Education:

Ph.D. in Mechanical & Aerospace Engineering, Princeton University, January 2001.

M.A. in Mechanical & Aerospace Engineering, Princeton University, June 1997.

B.M.E., Georgia Institute of Technology, March 1995. (Highest Honor, Cooperative Employment Plan)

Professional Experience:

Sep. 2014 – present	Professor Aerospace & Ocean Engineering Department Virginia Tech, Blacksburg, VA
Sep. 2008 – Aug. 2014	Associate Professor & Assistant Department Head for Graduate Studies Aerospace & Ocean Engineering Department Virginia Tech, Blacksburg, VA
Sep. 2006 – Aug. 2008	Associate Professor Aerospace & Ocean Engineering Department Virginia Tech, Blacksburg, VA
Jan. 2001 – Aug. 2006	Assistant Professor Aerospace & Ocean Engineering Department Virginia Tech, Blacksburg, VA
July 1995 – Dec. 2000	Graduate Research Assistant and Assistant in Instruction Mechanical & Aerospace Engineering Department Princeton University, Princeton, NJ
June 1991 - Sep. 1994	Student Employee, Cooperative Employment Plan Office of Scientific and Weapons Research (Directorate of Intelligence) & Office of Logistics (Directorate of Administration), Central Intelligence Agency, Washington, D.C. (Clearance Level: Top Secret, Sensitive Compartmented Information)

Professional Affiliations:

American Institute of Aeronautics and Astronautics (AIAA), Associate Fellow

Institute of Electrical and Electronics Engineers (IEEE), Senior Member

International Federation of Automatic Control (IFAC), Member

Association for Unmanned Vehicle Systems International (AUVSI), Ridge & Valley Chapter, Member & Treasurer

Professional & University Service:

Associate Editor, AIAA J. Guidance, Control, and Dynamics (2023 – present)

AIAA Atmospheric Flight Mechanics TC Member (2017 - present; Vice-chair, 2021 - 2023; Chair, 2023 - present)

IEEE CSS TC on Manufacturing Automation and Robotic Control (2017 – present)

IFAC TC on Marine Systems: TC 7.2 (2017 – present)

AUVSI Ridge & Valley Chapter (Treasurer, 2022 – present; President, 2019 – 2021; Secretary, 2016 – 2018)

VT University Promotion & Tenure Committee, College of Engineering (CoE) Representative (2016 – 2019)

VT AOE Diversity, Equity, & Inclusion Committee (2022 – 2023; Co-Chair, 2022 – 2023)

VT AOE Promotion & Tenure Committee (2014 – 2023; Chair, 2022 – 2023)

VT AOE Undergraduate Curriculum Committee (2012 – 2022)

VT AOE Dynamics, Control, & Estimation Group (2006 – present; Chair, 2006 – 2022)

Director, Virginia Center for Autonomous Systems (2006 – 2014)

VT AOE Assistant Department Head for Graduate Studies (2008 – 2014)

VT AOE Graduate Committee (Member, 2006 – 2019; Chair, 2007 – 2014)

Faculty Advisor, VT AUVSI Student Chapter (2018 – present)

Faculty Co-Advisor, VT Autonomous Underwater Vehicle Team (2002 – 2013)

Faculty Co-Advisor, VT Student Chapter of AIAA (2003 – 2008)

VT ADVANCE Advisory Board (2003 – 2008)

Chair, VT AOE Student Opportunities Committee (2003 – 2007)

Presbyterian Campus Ministry (Board, 2001 – 2007; Endowment Committee, 2007 – present)

Conference Organizing Service:

- General Chair: 15th IFAC Conf. Control Appl. in Marine Systems, Robotics and Vehicles: CAMS 2024
- Organizing Committee: 18th Int'l. Symposium on Mathematical Theory of Networks & Systems (2008)
- Organizing Committee: AUVSI Ridge & Valley Chapter Fall Symposium (2016 -- present)

Conference Program and/or Associate Editor Service:

- 14th IFAC Conf. Control Appl. in Marine Systems, Robotics and Vehicles: CAMS 2022 (Lyngby, Denmark, 2022)
- American Control Conf. (2006-2009, 2013-14, 2021, 2023)
- 1st IFAC Workshop on Guidance & Control of Underwater Vehicles (Newport, South Wales, U.K., 2003)

Reviewer for numerous journals and conferences. Special recognition:

- Excellent Reviewer (2015, 2017, 2022): AIAA J. Guidance, Control, & Dynamics
- Excellence in Review (2012): IEEE J. Oceanic Engineering

Honors & Awards:

AIAA SciTech Forum Atmospheric Flight Mechanics Best Student Paper Award (Gahan et al, 2023)

AIAA SciTech Forum Atmospheric Flight Mechanics Best Student Paper Award (Hopwood et al, 2022)

AIAA SciTech Forum Atmospheric Flight Mechanics Best Paper Award (McClelland & Woolsey, 2019)

National Academy of Sciences, Engineering and Medicine (NAS) Committee to Assess the Risks of Unmanned Aircraft Systems (UAS) Integration (2017-2018)

Virginia Tech College of Engineering Dean's Award for Excellence in Research (2017)

Virginia Tech Student Engineers Council Undergraduate Research Advisor of the Year (2015)

Virginia Tech Master Online Instructor (2013)

Virginia Tech College of Engineering Certificate of Teaching Excellence (2013)

SAE Ralph R. Teetor Educational Award (2008)

NSF Faculty Early Career Development (CAREER) Award (2002—2007)

ONR Young Investigator Program Award (2002—2005)

NASA Institute for Advance Concepts Fellow (2004-2005)

Virginia Tech College of Engineering Faculty Fellow (2003 – 2006)

Virginia Tech College of Engineering Dean's Award: Outstanding New Assistant Professor (2003)

NDSE (Department of Defense) Graduate Fellowship (1995–1998)

NSF Graduate Fellowship (deferred) (1995)

Guggenheim Fellowship (Princeton University) (1995)

Georgia Tech President's Scholar (1990 – 1995)

Tau Beta Pi Senior Engineering Cup (Georgia Tech) (1995)

College of Engineering Award (Georgia Tech) (1994)

CIA Exceptional Performance Award (1993)

Publications:1

Journal publications (peer-reviewed):

- [1] "Wind estimate uncertainty quantification and sensitivity analysis using generalized polynomial chaos," K. C. Gahan*, J. Hopwood", and C. A. Woolsey (In review.)
- [2] "Wind estimation using an $H\infty$ filter with fixed-wing aircraft flight test results," K. C. Gahan*, J. Hopwood", and C. A. Woolsey (In review.)
- [3] "Performance analysis of three predictors for mitigating input and output time delays," N. Sakib*, Z. Ahmed*, C. A. Woolsey (In review.)
- [4] "Depth dependent added mass computations using impulse motion simulations for shallowly submerged vehicles- Part 1: Accelerating from rest", W. Lambert*, S. Brizzolara, and C. A. Woolsey. (In review.)
- [5] "Depth dependent added mass computations using impulse motion simulations for shallowly submerged vehicles- Part 2: Accelerating from steady forward velocity", W. Lambert*, S. Brizzolara, and C. A. Woolsey. (In review.)
- [6] "A survey of indirect wind estimation methods using small uncrewed aerial vehicles," Z. Ahmed*, M. Halefom*, and C. A. Woolsey. *AIAA. J. Aerospace Information Systems* (To appear.)
- [7] "Unsteady aerodynamics in model-based wind estimation from small, fixed-wing aircraft motion," M. Halefom*, J. Hopwood*, and C. A. Woolsey. *AIAA J. Guidance, Control, and Dynamics* (To appear.) [10.2514/1.G007836]
- [8] "A structure-inspired disturbance observer for finite-dimensional mechanical systems," Y.-C. Chen* and C. A. Woolsey. *IEEE Trans. Control Systems Tech.* **32**(2), pp. 440-455, March 2024 [10.1109/TCST.2023.3327510]
- [9] "Spin aerodynamic modeling for a fixed-wing aircraft using flight data," J. L. Gresham*, B. M. Simmons*, J. W. Hopwood*, and C. A. Woolsey. *AIAA J. Aircraft* **61**(1), pp. 128-139, January 2024 [10.2514/1.C036835]
- [10] "Virginia Tech advanced towing carriage," C. Gilbert, M. Javaherian, C. Woolsey, and M. Shepheard, *Part M: Journal of Engineering for the Maritime Environment* **237**(4), pp. 867-877, November 2023 [10.1177/14750902231166958]

¹The superscript * in an author list denotes a postdoctoral, graduate, undergraduate, or high school research assistant or a visiting scholar advised or co-advised by C. Woolsey.

- [11] "A study of the wind sensing performance of pusher and puller hexacopter small unmanned aircraft," J. González -Rocha*, P. Sharma, E. Atkins, and C. A. Woolsey. *AIAA J. Aircraft* **60**(5), pp. 1712-1720, September–October 2023. [10.2514/1.C036792]
- [12] "Flight-test system identification techniques and applications for small, low-cost, fixed-wing aircraft," B. M. Simmons*, J. L. Gresham*, and C. A. Woolsey, *AIAA J. Aircraft* **60**(5), pp. 1503-1521, September–October 2023 [10.2514/1.C037260]
- [13] "A free surface corrected lumped parameter model for near-surface horizontal maneuvers of underwater vehicles in waves," W. Lambert*, L. Miller, S. Brizzolara, and C. A. Woolsey, *Ocean Engineering* **278**, June 2023 [10.1016/j.oceaneng.2023.114364]
- [14] "Experimental validation of port-Hamiltonian based control of fixed wing unmanned aircraft," J.-M. Fahmi*, J. Gresham*, and C. A. Woolsey. *AIAA J. Guidance, Control, and Dynamics* **46**(6), pp. 1169-1175, June 2023 [10.2514/1.G007018]
- [15] "Nonlinear dynamic modeling for aircraft with unknown mass properties using flight data," B. M. Simmons*, J. L. Gresham*, and C. A. Woolsey. *AIAA J. Aircraft* **60**(3), pp. 968-980, May-June 2023 [10.2514/1.C037259]
- [16] "Remote uncorrelated pilot input excitation assessment for unmanned aircraft aerodynamic modeling," J. L. Gresham*, B. M. Simmons*, J.-M. W. Fahmi*, J. W. Hopwood*, and C. A. Woolsey. *AIAA J. Aircraft* **60**(3), pp. 955-967, May–June 2023 [10.2514/1.C036942]
- [17] "The effect of a linear free surface boundary condition on the steady-state wave-making of shallowly submerged underwater vehicles," W. Lambert*, S. Brizzolara, and C. A. Woolsey, *J. Marine Science and Engineering* May 2023. [10.3390/jmse11050981]
- [18] "Robust stall spin flight path control with flight test validation," J. Hopwood*, J. Gresham*, and C. A. Woolsey. AIAA J. Guidance, Control, and Dynamics 46(3), pp. 553-559, March 2023 [10.2514/1.G007016]
- [19] "Time delay mitigation in aerial telerobotic operations using heterogeneous stereo vision systems," N. Sakib*, K. C. Gahan*, and C. A. Woolsey *AIAA*. *J. Aerospace Information Systems* **20**(9), pp. 526-545, 2023. [10.2514/1.I011204]
- [20] "A maneuvering model for an underwater vehicle near a free surface—Part III: Simulation and control under waves," F. Valentinis, T. Battista*, and C. A. Woolsey. *IEEE J. Oceanic Engineering*, **48**(3), pp. 752-777, 2023. [10.1109/JOE.2023.3234811]
- [21] "A maneuvering model for an underwater vehicle near a free surface Part II: Incorporation of the free surface memory," T. Battista*, F. Valentinis, and C. A. Woolsey. *IEEE J. Oceanic Engineering*, **48**(3), pp. 740-751, 2023. [10.1109/JOE.2022.3229919]
- [22] "Aero-propulsive modeling for propeller aircraft using flight data," B. Simmons*, J. Gresham*, and C. A. Woolsey. *AIAA J. Aircraft* **60**(1), pp. 81-96, 2023. [10.2514/1.C036773]
- [23] "Bridge inspection component registration for damage evolution," E. Bianchi, N. Sakib*, M. Hebdon, and C. A. Woolsey. *J. Structural Health Monitoring*. **22**(1), pp. 472-495, January 2023. [10.1177/14759217221083647]
- [24] "Performance assessment of energy-preserving, adaptive time-step variational integrators," H. Sharma, J. Borggaard, M. Patil, and C. A. Woolsey. *Comm. Nonlinear Science and Numerical Simulation*. **114**, November 2022 [10.1016/j.cnsns.2022.106646]
- [25] "Lift enhancement by a flapped trailing edge at low Reynolds number: A frequency response approach," H. Shehata*, M. Y. Zakaria, M. Hajj, and C. A. Woolsey. *J. Fluids and Structures*. **110**, April 2022. [10.1016/j.jfluidstructs.2022.103518]
- [26] "On closed-loop vibrational control of underactuated mechanical systems," S. Tahmasian and C. A. Woolsey. *Nonlinear Dynamics*. **108**, pp. 329–347, January 2022. [10.1007/s11071-022-07214-y]
- [27] "Port-Hamiltonian flight control of a fixed-wing aircraft," J.-M. Fahmi* and C. A. Woolsey. *IEEE Trans. Control Systems Technology* **30**(1), pp. 408-415, January 2022. [10.1109/TCST.2021.3059928]
- [28] "Parameter computation for a Lagrangian mechanical system model of a submerged vessel moving near a free surface," S. Jung*, S. Brizzolara, and C. A. Woolsey. *Ocean Engineering*, **230**, June 2021. [10.1016/j.oceaneng.2021.108988]
- [29] "Scheduled imaging of multiple threat aircraft using a modified traveling salesman problem," C. Kang* and C. A. Woolsey AIAA. J. Aerospace Information Systems, **18**(7), pp. 476-486, 2021 [10.2514/1.I010871]
- [30] "Development of a peripheral-central vision system for small UAS tracking," C. Kang*, H. Chaudhry, C. A. Woolsey, and K. Kochersberger. *AIAA*. *J. Aerospace Information Systems*, **18**(9), pp. 645-658, 2021. [10.2514/1.I010909]

- [31] "An approach for computing parameters for a Lagrangian nonlinear maneuvering and seakeeping model of submerged vessel motion," S. Jung*, S. Brizzolara, and C. A. Woolsey. *IEEE J. Oceanic Engineering*, **46**(3), pp. 749 764, March 2021. [10.1109/JOE.2021.3052657]
- [32] "Model-based path prediction for fixed-wing unmanned aircraft using pose estimates," C. Kang* and C. A. Woolsey. *Aerospace Science and Technology* 105, October 2020, 106030 [10.1016/j.ast.2020.106030]
- [33] "A review of structure-preserving numerical methods for engineering applications," H. Sharma*, M. Patil, and C. A. Woolsey. *Computer Methods in Applied Mechanics and Engineering* **366**, July 2020, 113067 [10.1016/j.cma.2020.113067]
- [34] "Effects of two modeling assumptions on wind reconstruction from longitudinal aircraft motion," H. McClelland* and C. A. Woolsey AIAA J. Guidance, Control, and Dynamics 43(6), pp. 1069-1081, June 2020 [10.2514/1.G004224]
- [35] "Wind profiling in the lower atmosphere from wind-induced perturbations to multirotor UAS," J. González-Rocha*, S. F. J. De Wekker, S. D. Ross, and C. A. Woolsey *Sensors*, 2020. [10.3390/s20051341]
- [36] "A maneuvering model for an underwater vehicle near a free surface Part I: Motion without memory effects," T. Battista*, F. Valentinis, and C. Woolsey. *IEEE J. Oceanic Engineering* **45**(1), pp. 212-226, January 2020. [10.1109/JOE.2018.2871650]
- [37] "Nonlinear model identification methodology for small, fixed-wing, unmanned aircraft," B. Simmons*, H. G. McClelland*, and C. A. Woolsey. *AIAA J. Aircraft* **56**(3), pp. 1056-1067, May-June 2019. [10.2514/1.C035160]
- [38] "A method for detecting atmospheric Lagrangian coherent structures using a single fixed wing unmanned aircraft system," P. Nolan, H. G. McClelland*, C. A. Woolsey, S. D. Ross, *Sensors*, 2019. [10.3390/s19071607]
- [39] "Sensing wind from quadrotor motion," J. González-Rocha*, C. A. Woolsey, C. Sultan, and S. F. J. De Wekker. *AIAA J. Guidance, Control, and Dynamics* **42**(4), pp. 836-852, April 2019. [10.2514/1.G003542]
- [40] "Nonlinear control of a subscale submarine in emergency ascent," F. Valentinis and C. A. Woolsey. *Ocean Engineering* **171**, pp. 646-662, January 2019. [10.1016/j.oceaneng.2018.11.029]
- [41] "Workspace modeling and path planning for truss structure inspection by small UAS," A. Das* and C. A. Woolsey. *AIAA J. Aerospace Information Systems* **16**(1), pp. 37-51, January 2019. [10.2514/1.I010634]
- [42] "Energy-preserving variational integrators for forced Lagrangian systems," H. Sharma*, M. Patil, and C. A. Woolsey. *Communications in Nonlinear Science and Numerical Simulation* **64**, pp. 159-177, November 2018. [10.1016/j.cnsns.2018.04.015]
- [43] "On averaging and input optimization of high-frequency mechanical control systems," S. Tahmasian*, D. W. Allen*, and C. A. Woolsey. *J. Vibration and Control* **24**(5), pp. 937-955, May 2018.

 [10.1177/1077546316655706]
- [44] "Flight control of biomimetic air vehicles using vibrational control and averaging," S. Tahmasian* and C. A. Woolsey. *J. Nonlinear Science* **27**(4), pp. 1193–1214, August 2017. [10.1007/s00332-016-9334-5]
- [45] "A comparison of three approaches to atmospheric source localization," H. M. Abdelghaffar, C. A. Woolsey, and H. A. Rakha, *AIAA J. Aerospace Information Systems*, 14(1), pp. 40-52, January 2017. [10.2514/1.I010440]
- [46] "Optimal paths in still air for a sailplane with a quadratic glide polar," A. Wolek* and C. A. Woolsey. *Technical Soaring* **40**(2), pp. 9-23, April-June 2016.
- [47] "Time-optimal path planning for a kinematic car with variable speed," A. Wolek*, E. M. Cliff, and C. A. Woolsey. *AIAA J. Guidance, Control, and Dynamics* **39**(10), pp. 2374-2390, 2016. [10.2514/1.G001317]
- [48] "Fuel/time optimal relative trajectories for a satellite near a perturbed, elliptical orbit," A. Rogers*, C. A. Woolsey, J. Black, and R. McGwier. *AIAA J. Spacecraft and Rockets* **53**(5), pp. 811-821, 2016. [10.2514/1.A33365]
- [49] "Energy-optimal paths for a glider with speed and load factor controls," A. Wolek*, E. M. Cliff, and C. A. Woolsey. *AIAA J. Guidance, Control, and Dynamics* **39**(2), pp. 397-408, February 2016. [10.2514/1.G001345]
- [50] "Geometric control approach to longitudinal stability of flapping flight," H. Taha, C. A. Woolsey, and M. Hajj. *AIAA J. Guidance, Control, and Dynamics* **39**(2), pp. 214-226, February 2016. [10.2514/1.G001345]
- [51] "Exploring the oceans of Europa with biologically-inspired underwater vehicles," D. W. Allen*, M. C. Jones*, L. S. McCue, W. B. Moore, M. Philen, and C. A. Woolsey. *J. the British Interplanetary Society* **68**, pp. 251-264, August 2015.

- [52] "Geometric control of a flapping plate," H. E. Taha and C.A. Woolsey. *J. Vibration and Control* **21**(11):2124–2133, August 2015. [10.1177/1077546313506924]
- [53] "A control design method for underactuated mechanical systems using high frequency inputs," S. Tahmasian* and C. A. Woolsey. *ASME J. Dynamic Systems, Measurement, and Control* **137**(7), July 2015. [10.1115/1.4029627]
- [54] "Feasible Dubins paths in the presence of unknown, unsteady velocity disturbances," A. Wolek* and C. A. Woolsey. *AIAA J. Guidance, Control, and Dynamics* **38**(4), pp. 782-786, April 2015. [10.2514/1.G000629]
- [55] "The need for higher-order averaging in the stability analysis of hovering, flapping-wing flight", H. Taha, S. Tahmasian*, C. A. Woolsey, A. Nayfeh, and M. Hajj. *Bioinspiration and Biomimetics* **10**(1), February 2015. (Paper selected as one of the *Bioinspiration & Biomimetics* "Highlights" for 2015.) [10.1088/1748-3190/10/1/016002]
- [56] "Integration and testing of a surface plasmon resonance sensor with a small unmanned aerial vehicle," M. Palframan*, H. Gruszewski, D. Schmale, III, and C. A. Woolsey. *J. Unmanned Vehicle Systems* **2**, pp. 103–118, October 2014. [10.1139/juvs-2013-0019]
- [57] "Dynamics of underwater gliders in currents," S. Fan* and C. A. Woolsey. *Ocean Engineering* **84**, pp. 249–258, July 2014. [10.1016/j.oceaneng.2014.03.024]
- [58] "Stabilization of flapping-wing micro-air vehicles in gust environments," M. Bhatia, M. Patil, C. A. Woolsey, B. Stanford and P. Beran. *AIAA J. Guidance, Control, and Dynamics* **37**(2):592-607, March 2014. [10.2514/1.59875]
- [59] "An efficient motion control system for underwater gliders," N. Mahmoudian* and C. Woolsey. *Nonlinear Engineering: Modeling and Application*. Vol. 2, pp. 63-77, 2013. [10.1515/nleng-2012-0011]
- [60] "Elements of underwater glider performance and stability," S. Fan* and C. Woolsey. *Marine Technology Society Journal*, **47**(3), pp. 81-98, May/June 2013. [10.1515/nleng-2012-0011]
- [61] "Modeling, identification, and control of an unmanned surface vehicle," C. Sonnenburg* and C. A. Woolsey. *J. Field Robotics*, **30**(3), pp. 371-398, May/June 2013. [10.1002/rob.21452]
- [62] "Vehicle motion in currents," P. Thomasson and C. A. Woolsey. *IEEE J. Oceanic Engineering*, **38**(2), pp. 226-242, April 2013. [10.1109/JOE.2013.2238054]
- [63] "Unmanned aerial vehicle coordination on closed convex paths in wind" L. Techy*, D. Paley, and C. A. Woolsey. *AIAA J. Guidance, Control, and Dynamics*, **33**(6), pp. 1946-1951, November-December 2010. [10.2514/1.47655]
- [64] "Backstepping for synchronization of nonlinear dynamical systems," K. Listmann, J. Adamy, and C. A. Woolsey. *Automatisierungstechnik*, pp. 425-434, August 2010.
- [65] "Coordinated aerobiological sampling of a plant pathogen in the lower atmosphere using two autonomous unmanned aerial vehicles," L. Techy*, D. Schmale, III, and C. A. Woolsey. *J. Field Robotics* **27**(3), pp. 335–343, May/June 2010. [10.1002/rob.20335]
- [66] "Fast estimation for range identification in the presence of unknown motion parameters," L. Ma*, C. Cao, N. Hovakimyan, C. Woolsey, and W. Dixon. *IMA J. Applied Mathematics*, **75**(2), pp. 165-189, February 2010. [10.1093/imamat/hxq008]
- [67] "Approximate analytical turning conditions for underwater gliders and implications for path planning," N. Mahmoudian*, J. Geisbert*, and C. Woolsey. *IEEE J. Oceanic Engineering* **35**(1), pp. 131-143, January 2010. [10.1109/JOE.2009.2039655]
- [68] "Minimum-time path planning for unmanned aerial vehicles in steady uniform winds," L. Techy* and C. A. Woolsey. *AIAA J. Guidance, Control, and Dynamics*, **32**(6), pp. 1736-1746, November-December 2009. [10.2514/1.44580]
- [69] "Cross-track control of a slender, underactuated AUV using potential shaping," C. A. Woolsey and L. Techy*. *Ocean Engineering: Special Issue on AUVs* **36**, pp. 82-91, January 2009. [10.1016/j.oceaneng.2008.07.010]
- [70] "Planar flow model identification for improved navigation of small AUVs," J. Petrich, C. A. Woolsey, and D. J. Stilwell. *Ocean Engineering: Special Issue on AUVs.* **36**, pp. 119-131, January 2009. [10.1016/j.oceaneng.2008.10.002]
- [71] "Global directional control of a slender AUV," H.-Y. Kim* and C. A. Woolsey. *AIAA J. Guidance, Control, and Dynamics* **30**(1), pp. 255-259, January-February 2007. [10.1016/j.oceaneng.2008.07.010]
- [72] "Exploring Titan with autonomous, buoyancy-driven gliders," M. Morrow*, C. A. Woolsey, and G. Hagerman. *J. the British Interplanetary Society* **59**(1), pp. 27-34, January 2006.

- [73] "Backstepping control of an SMA-actuated robotic arm," M. H. Elahinia, J. Koo, M. Ahmadian, and C. A. Woolsey. *J. Vibration and Control* 11(3), pp. 407-429, March 2005. [10.1177/1077546305051201]
- [74] "Reduced Hamiltonian dynamics for a rigid body/mass particle system," C. Woolsey. *AIAA J. Guidance, Control, and Dynamics* **28**(1), pp. 131-138, January-February 2005. [10.2514/1.5409]
- [75] "Controlled Lagrangian systems with gyroscopic forcing and dissipation," C. Woolsey, C. K. Reddy*, A. M. Bloch, D. E. Chang, N. E. Leonard, J. E. Marsden. *European J. Control (Special Issue on Lagrangian and Hamiltonian Methods for Nonlinear Control)* **10**(5), pp. 478-496, Dec. 2004. [10.3166/ejc.10.478-496]
- [76] "Stabilizing underwater vehicle motion using internal rotors," C. Woolsey and N. E. Leonard. *Automatica*, **38**(12), pp. 2053-2062, December 2002. [10.1016/S0005-1098(02)00136-X]
- [77] "The equivalence of controlled Lagrangian and controlled Hamiltonian systems," D. E. Chang, A. M. Bloch, N. E. Leonard, J. E. Marsden, and C. Woolsey *Control, Optimisation, and Calculus of Variations (Special Issue Dedicated to J. L. Lions)* **8**, pp. 393-422, June 2002. [10.1051/cocv:2002045]
- [78] "Transfer functions for acoustic emission transducers using laser interferometry," L. J. Jacobs and C. Woolsey, J. the Acoustical Society of America, 94 (6), pp. 3506-3508, December 1993. [10.1121/1.407205]

Book chapters and other journal publications:

- [79] "Model-based path planning," A. Wolek and C. A. Woolsey, *Sensing and Control for Autonomous Vehicles:*Applications to Land, Water and Air Vehicles, T. I. Fossen, K. Y. Pettersen, and H. Nijmeijer, Eds., Springer:
 Lecture Notes in Control and Information Sciences, pp. 183-206, 2017. [10.1007/978-3-319-55372-6_9]
- [80] "Design and modeling of a two-stage towed sensor platform: A passively and actively stabilized towfish for experimental ocean science," E. M. Schuch*, A. C. Linklater*, and C. A. Woolsey. *Sea Technology* 47(7), pp. 20-23, July 2006. [10.1109/OCEANS.2005.1640001]
- [81] "Book Review: Marine Control Systems: Guidance, Navigation, and Control of Ships, Rigs, and Underwater Vehicles by T. I. Fossen," C. A. Woolsey. AIAA J. Guidance, Control, and Dynamics 28(3), pp. 574-575, May-June 2005. [10.2514/1.17190]

<u>Technical Reports</u>²

- [82] "Hermite-based, one-step, variational and Galerkin time integrators for mechanical systems," H. Sharma*, M. Patil, and C. A. Woolsey. arXiv:2201.07327
- [1] "Design and Testing of a Pneumatically Propelled Underwater Glider for Shallow Water," A. Wolek*, T. Gode*, C. A. Woolsey, J. Quenzer and K. A. Morgansen. VaCAS Technical Report No. VaCAS-2015-01.
- [2] "Exploration of Under-ice Regions with Ocean Profiling Agents (EUROPA)," D. W. Allen*, M. Jones*, L. McCue, C. A. Woolsey, and W. B. Moore. VaCAS Technical Report No. VaCAS-2013-01.
- [3] "Vehicle Dynamics in Currents," C. Woolsey. VaCAS Technical Report No. VaCAS-2011-01.
- [4] "Dynamics and Control of Underwater Gliders II: Motion Planning and Control," N. Mahmoudian* and C. Woolsey. VaCAS Technical Report No. VaCAS-2010-02.
- [5] "Control-Oriented Planar Motion Modeling of Unmanned Surface Vehicles," C. Sonnenburg*, A. Gadre, D. Horner, S. Krageland, A. Marcus, D. J. Stilwell, and C. A. Woolsey. VaCAS Technical Report No. VaCAS-2010-01.
- [6] "Long-Baseline Ranging System for Acoustic Underwater Localization of the Seaglider Underwater Glider," L. Techy, K. A. Morgansen, and C. A. Woolsey. UWAA Technical Report No. UWAATR-2010-0001.
- [7] "Optimal Control of an Undersea Glider in a Symmetric Pull-up," R. Kraus*, E. Cliff, C. Woolsey, and J. Luby. VaCAS Technical Report No. VaCAS-2008-03.
- [8] "Dynamics and Control of Underwater Gliders I: Steady Motions," N. Mahmoudian*, J. Geisbert*, and C. Woolsey. VaCAS Technical Report No. VaCAS-2007-01.

² VaCAS technical reports available at https://vtechworks.lib.vt.edu/handle/10919/19352

Conference publications (accepted based on full paper review):

- [1] "Surface contour following by an underwater vehicle with integral action," I. Willebeek-LeMair*, C. Grant*, William Lambert*, S. Brizzolara*, and C. A. Woolsey, *Proc. 15th IFAC Conf. on Control Applications in Marine Systems, Robotics, and Vehicles (CAMS)*, Blacksburg, VA, September 2024 (To appear.)
- [2] "Robustness and convergence analysis of first-order distributed optimization algorithms over subspace constraints," D. Marquis, D. Abou Jaoude, M. Farhood, and C. Woolsey *American Control Conference*, San Diego, California, June 2023. [10.23919/ACC55779.2023.10156353]
- [3] "A structure-inspired disturbance observer for an underwater vehicle," Y.-C. Chen* and C. A. Woolsey, *Proc. 14th IFAC Conf. on Control Applications in Marine Systems, Robotics, and Vehicles (CAMS)*, Copenhagen, Denmark, September 2022. [10.1016/j.ifacol.2022.10.477]
- [4] "Stability under state estimate feedback using an observer characterized by uniform semi-global practical asymptotic stability," Y.-C. Chen* and C. A. Woolsey, *American Control Conference*, Atlanta, GA, June 2022. [10.23919/ACC53348.2022.9867255]
- [5] "Axial force measurements for a towed biolocomotion emulator," K. Q. Nguyen*, C. A. Woolsey, R. V. Datla, U. Chung, and M. R. Hajj, *Proc.* 13th *IFAC Conf. on Control Applications in Marine Systems, Robotics, and Vehicles (CAMS)*, Online Conference (from Oldenburg, Germany) during Sept 22-24, 2021.
- [6] "Vibrational control of a 2-link mechanism," Z. Ahmed*, S. Tahmasian, and C. A. Woolsey. *ASME Dynamic Systems and Control Conference*, Virtual Conference, October 2020. [10.1115/DSCC2020-3257]
- [7] "Passivity-based disturbance observer design," Y.-C. Chen* and C. A. Woolsey. *ASME Dynamic Systems and Control Conference*, Virtual Conference, October 2020. [10.1115/DSCC2020-3287]
- [8] "Symplectic accelerated optimization on SO(3) with Lie group variational integrators," H. Sharma*, T. Lee, M. Patil, and C. A. Woolsey, *Proc. American Control Conference*, Virtual Conference, June 2020. [10.23919/ACC45564.2020.9147775]
- [9] "Energy-preserving, adaptive time-step Lie group variational integrators for rigid body motion in SE(3)," H. Sharma*, M. J. Patil, and C. A. Woolsey. *Proc. Conference on Decision and Control*, Nice, France, December 2019. [10.1109/CDC40024.2019.9029731]
- [10] "Longitudinal, near-surface maneuvering of a prolate spheroid," Y.-C. Chen*, S. Jung*, and C. A. Woolsey, *Proc. 12th IFAC Conf. on Control Applications in Marine Systems, Robotics, and Vehicles (CAMS)*, Daejeon, South Korea, September 2019. [10.1016/j.ifacol.2019.12.315]
- [11] "The effects of flexible propulsors on hydrodynamic forces," H. Shehata*, M. Hajj, C. A. Woolsey, and S. Ragab, *Proc. 12th IFAC Conf. on Control Applications in Marine Systems, Robotics, and Vehicles (CAMS)*, Daejeon, South Korea, September 2019. [10.1016/j.ifacol.2019.12.276]
- [12] "Hydrodynamic performance of a modular biolocomotion emulator," H. Shehata*, C. A. Woolsey, and M. Hajj, *Proc. 12th IFAC Conf. on Control Applications in Marine Systems, Robotics, and Vehicles (CAMS)*, Daejeon, South Korea, September 2019. [10.1016/j.ifacol.2019.12.274]
- [13] "Stable, planar self propulsion using a hinged flap," A. A. Hussein, M. R. Hajj, C. A. Woolsey, *Proc. 11th IFAC Conf. on Control Applications in Marine Systems, Robotics, and Vehicles (CAMS)*, Opatija, Croatia, September 2018. [10.1016/j.ifacol.2018.09.455]
- [14] "Modeling and roadmap generation for truss inspection by small UAS," A. Das and C. A. Woolsey, *Proc. European Control Conference*, Limmasol, Cyprus, June 2018. [10.23919/ECC.2018.8550276]
- [15] "Sense and avoid based on computer vision pose estimation for small UAS," C. Kang*, J. Davis*, C. A. Woolsey, and S. Choi, *Proc. IEEE/RSJ Conference on Intelligent Robots and Systems*, Vancouver, BC, Canada, September 2017. [10.1109/IROS.2017.8206188]
- [16] "An energy-Casimir approach to underwater vehicle depth and heading regulation in short crested waves," T. Battista*, S. Jung*, C. Woolsey, and E. Paterson, *Proc. Conference on Control Technology and Applications*, Kohala Coast, HI, August 2017 (Invited). [10.1109/CCTA.2017.8062466]
- [17] "A dynamic model for underwater vehicle maneuvering near a free surface," T. Battista, C. A. Woolsey, T. Perez, and F. Valentinis, *Proc. 10th IFAC Conf. on Control Applications in Marine Systems (CAMS)*, Trondheim, Norway, September 2016. [Best Student Paper Award] [10.1016/j.ifacol.2016.10.323]
- [18] "Underwater vehicle depth and attitude regulation in plane progressive waves," T. Battista*, C. A. Woolsey, L. McCue-Weil, E. Paterson, and F. Valentinis, *Proc. Conference on Decision and Control*, Kyoto, Japan, December 2015. [10.1109/CDC.2015.7402906]

- [19] "Nonlinear tracking of optimal maneuvers in spacecraft formations," A. Rogers, R. McGwier, and C. A. Woolsey, *Proc. American Control Conference*, Chicago, IL, July 2015. [10.1109/ACC.2015.7172258]
- [20] "Underwater vehicle control and estimation in nonuniform currents," S. Fan and C. A. Woolsey, *Proc. American Control Conference*, pp. 1402-1407, Washington, D.C., June 2013 (Invited Paper). [10.1109/ACC.2013.6580032]
- [21] "Control of underactuated nonlinear systems using high frequency input," S. Tahmasian*, H. Taha, and C. A. Woolsey, *Proc. American Control Conference*, pp. 603-608, Washington, D.C., June 2013 (Invited Paper). [10.1109/ACC.2013.6579903]
- [22] "A geometric control approach for optimum maneuverability of flapping wing MAVs near hover," H. Taha, C. A. Woolsey, and M. Hajj, *Proc. American Control Conference*, pp. 597-602, Washington, D.C., June 2013 (Invited Paper). [10.1109/ACC.2013.6579902]
- [23] "Disturbance rejection in Dubins path planning," A. Wolek* and C. A. Woolsey, *Proc. American Control Conference*, pp. 4873-4878, Montreal, Canada, June 2012. [10.1109/ACC.2012.6315582]
- [24] "Control of flapping wing micro-air vehicles using variable stiffness membrane wings," L. Hale,* M. Patil, and C. A. Woolsey, *Proc. American Control Conference*, pp. 2521-2526, Montreal, Canada, June 2012. [10.1109/ACC.2012.6315582]
- [25] "Long-baseline acoustic localization of the Seaglider underwater glider," L. Techy*, K. Morgansen, and C. A. Woolsey, Proc. American Control Conference, San Francisco, CA, July 2011.
 [10.1109/ACC.2011.5991416]
- [26] "Pose estimation from visual measurements using epipolar geometry," M. J. Monda* and C. A. Woolsey, *Proc.* 49th IEEE Conference on Decision and Control, pp. 1633-1638, Atlanta, GA, December 2010. [10.1109/CDC.2010.5718182]
- [27] "Planar path planning for flight vehicles in wind with turn rate and acceleration bounds," L. Techy*, C. A. Woolsey, and K. Morgansen, *International Conference on Robotics & Automation*. Anchorage, AK, May 2010. [10.1109/ROBOT.2010.5509862]
- [28] "UAV coordination on convex curves in wind: An environmental sampling application," L. Techy*, D. A. Paley, and C. A. Woolsey, 2009 European Control Conference, pp. 4967-4972, Budapest, Hungary, August 2009. [10.23919/ECC.2009.7075187]
- [29] "Passivity-based coordination of multi-agent systems: A backstepping approach," K. D. Listmann, C. A. Woolsey and J. Adamy, 2009 European Control Conference., pp. 2450-2455, Budapest, Hungary, August 2009. [10.23919/ECC.2009.7074773]
- [30] "Estimation of an affine motion", L. Ma*, C. Cao, N. Hovakimyan, C. Woolsey, and G. Hu, 2009 American Control Conference, pp. 5085 5090, St. Louis, MO, June 2009. [10.1109/ACC.2009.5160177]
- [31] "Underwater glider motion control," N. Mahmoudian* and C. A. Woolsey, *Proc.* 47th IEEE Conference on Decision and Control, pp. 552 557, Cancun, Mexico, December 2008. [10.1109/CDC.2008.4739432]
- [32] "Path planning for efficient UAV coordination in aerobiological sampling missions," L. Techy*, C. A. Woolsey, D. G. Schmale III, *Proc.* 47th IEEE Conference on Decision and Control, pp. 2814 2819, Cancun, Mexico, December 2008. [10.1109/CDC.2008.4739456]
- [33] "Optimal control for an underwater glider: Avoiding stall in a symmetric pull-up," R. J. Kraus*, E. M. Cliff, J. C. Luby, and C. A. Woolsey. *Proc.* 18th International Symposium on Mathematical Theory of Networks and Systems, Blacksburg, VA, August 2008 (Invited paper.)
- [34] "L₁ adaptive control of a UAV for aerobiological sampling," J. Wang, V. Patel, C. A. Woolsey, N. Hovakimyan, and D. Schmale, III *2007 American Control Conference*, pp. 4660-4665, New York, NY. [10.1109/ACC.2007.4283121]
- [35] "Nonlinear control of a novel two-link pendulum," L. Techy*, C. K. Reddy*, C. A. Woolsey, C. Cao, and N. Hovakimyan 2007 American Control Conference, pp. 19-24, New York, NY. [10.1109/ACC.2007.4282946]
- [36] "Range identification in the presence of unknown motion parameters for perspective vision systems," L. Ma*, C. Cao, N. Hovakimyan, W. E. Dixon, and C. A. Woolsey 2007 American Control Conference, pp. 972-977, New York, NY. [10.1109/ACC.2007.4282941]
- [37] "Directional control of a slender, underactuated AUV using potential shaping," C. A. Woolsey *Proc.* 45th IEEE Conference on Decision and Control, pp. 6826-6831, San Diego, CA, December 2006 (Invited paper.) [10.1109/CDC.2006.377428]
- [38] "Energy shaping for vehicles with point mass actuators," C. K. Reddy* and C. A. Woolsey. *Proc. 2006 American Control Conference*, pp. 4291-4296, Minneapolis, MN. [10.1109/ACC.2006.1657393]

- [39] "Directional control of a streamlined underwater vehicle by feedback passivation," H.-Y. Kim* and C. Woolsey. *Proc. 2004 American Control Conference*, pp. 2998-3003, Boston, MA. [10.1109/ACC.2004.182744]
- [40] "Controlled Lagrangians with gyroscopic forcing: An experimental application," K. Reddy*, W. Whitacre*, and C. Woolsey. *Proc. 2004 American Control Conference*, pp. 511-516, Boston, MA. [10.23919/ACC.2004.1383654]
- [41] "Passive and active attitude stabilization for a tow-fish," C. Woolsey and A. Gargett. *Proc.* 41st IEEE Conference on Decision and Control, pp. 2099-2104, Las Vegas, NV, December 2002. (Invited paper.) [10.1109/CDC.2002.1184839]
- [42] "Hamiltonian attitude dynamics for a spacecraft with a point mass oscillator," C. Woolsey. *Proc.* 15th International Symposium on Mathematical Theory of Networks and Systems, Notre Dame, IN, August 2002. (Invited paper.)
- [43] "Moving mass control for underwater vehicles," C. Woolsey and N. E. Leonard. *Proc. 2002 American Control Conference.*, pp. 2824-2829, Anchorage, AK, May 2002. (Invited paper.) [10.1109/ACC.2002.1025217]
- [44] "Dissipation and controlled Euler-Poincaré systems," C. Woolsey, A. Bloch, N. E. Leonard, and J. Marsden. Proc. 40th IEEE Conference on Decision and Control, pp. 3378-3383, Orlando, FL, December 2001. [10.1109/CDC.2001.980356]
- [45] "Physical dissipation and the method of controlled Lagrangians," C. Woolsey, A. Bloch, N. E. Leonard, and J. Marsden. *Proc. 2001 European Control Conference*, pp. 2570-2575, Porto, Portugal, September 2001. [10.23919/ECC.2001.7076315]
- [46] "Modification of Hamiltonian structure to stabilize an underwater vehicle," C. Woolsey and N. E. Leonard, Proc. IFAC Workshop on Lagrangian and Hamiltonian Methods for Nonlinear Control, pp. 185-186, Princeton, NJ, March 2000.
- [47] "Asymptotic stabilization of Euler-Poincaré mechanical systems," A. Bloch, D. Chang, N. E. Leonard, J. Marsden and C. Woolsey, *Proc. IFAC Workshop on Lagrangian and Hamiltonian Methods for Nonlinear Control*, pp. 56-61 Princeton, NJ, March 2000. (Invited paper.) [10.1016/S1474-6670(17)35546-5]
- [48] "Global asymptotic stabilization of an underwater vehicle using internal rotors," C. Woolsey and N. E. Leonard, *Proc.* 38th IEEE Conference on Decision and Control, pp. 2527-2532, Phoenix, AZ, December 1999. [10.1109/CDC.1999.831308]
- [49] "Underwater vehicle stabilization using internal rotors," C. Woolsey and N. E. Leonard, *Proc. 1999 American Control Conference*, pp. 3417-3421, San Diego, CA, June 1999. [10.1109/ACC.1999.782399]
- [50] "Internal actuation for intelligent underwater vehicle control," N. E. Leonard and C. Woolsey, *Proc. 10th Yale Workshop on Adaptive and Learning Systems*, pp. 295-300, New Haven, CT, June 1998. (Invited paper.)
- [51] "Design and analysis of an underwater vehicle for controlled gliding," J. Graver, J. Liu, C. Woolsey, and N. E. Leonard, *Proc. 1998 Conference on Information Sciences and Systems*, pp. 801-806, Princeton, NJ, March 1998.

Conference publications (accepted based on an abstract):

- "Kalman filter-based framework for predicting aerial telerobotic operations with input and output delays," N. Sakib, Z. Ahmed, and C. A. Woolsey, *CEAS Conf. on Guidance, Navigation and Control (EuroGNC)*, Bristol, U.K., June 2024.
- [53] "Uncertainty in wind estimates, Part 1: Analysis using generalized polynomial chaos," K. C. Gahan*, J. Hopwood* and C. A. Woolsey, *AIAA SciTech Forum 2024*, Orlando, FL, January 2024. [Invited.] [10.2514/6.2024-2824]
- [54] "Uncertainty in wind estimates, Part 2: H∞ filtering using generalized polynomial chaos," K. C. Gahan*, J. Hopwood* and C. A. Woolsey, AIAA SciTech Forum 2024, Orlando, FL, January 2024. [Invited.] [10.2514/6.2024-2825]
- [55] "The invariant extended Kalman filter for wind estimation using a small fixed-wing UAV in horizontal-plane flight," Z. Ahmed* and C. A. Woolsey, *AIAA SciTech Forum 2024*, Orlando, FL, January 2024. [Invited.] [10.2514/6.2024-2656]

- [56] "Robust linear parameter-varying control for safe and effective unstable aircraft system identification," J. Hopwood* and C. A. Woolsey, *AIAA SciTech Forum 2024*, Orlando, FL, January 2024. [Invited.] [10.2514/6.2024-1305]
- [57] "Development and evaluation of multirotor flight dynamic models for estimation and control," J. Hopwood*, B. Simmons, C. A. Woolsey, and J. K. Cooper, AIAA SciTech Forum 2024, Orlando, FL, January 2024. [10.2514/6.2024-1307]
- [58] "Relative depth-keeping of an underactuated, near-surface underwater vehicle in waves," C. Grant* and C. A. Woolsey, *Proc. MTS/IEEE OCEANS 2023*, Biloxi, MS, September 2023.
 [10.23919/OCEANS52994.2023.10336969]
- [59] "Intelligent wind estimation for chemical source localization," J. Cooper, J. Hopwood*, C. A. Woolsey, S. De Wekker, and M. DeVore, *Proc. Vertical Flight Society*, Miami, FL, May 2023.
- [60] "Wind estimation using a fixed-wing model-based H∞ filter," K. C. Gahan*, J. Hopwood*, and C. A. Woolsey, *AIAA SciTech Forum 2023*, National Harbor, MD, January 2023. [10.2514/6.2023-2252] **Award:** 2023 AIAA Atmospheric Flight Mechanics Best Student Paper
- [61] "Dynamic network-based probabilistic route planner and validation with flight test," R. Prasad, J. Shim, J.-Y. Choi, J.-M Fahmi*, J. Jang, G. Lee, N. Song. C. A. Woolsey, and S. Choi, *AIAA SciTech Forum 2023*, National Harbor, MD, January 2023. [10.2514/6.2023-2661]
- [62] "Nonlinear dynamic model identification for aircraft with unknown mass properties using flight data," B. Simmons*, J. Gresham*, and C. A. Woolsey, *AIAA SciTech Forum 2023*, National Harbor, MD, January 2023. [10.2514/6.2023-0040]
- [63] "Modeling, simulation, and control of an aircraft with adjustable wing dihedral," M. Zakaria*, R. Fisher*, and C. A. Woolsey, *AIAA SciTech Forum 2023*, National Harbor, MD, January 2023. [10.2514/6.2023-0036]
- [64] "A strip theory and CFD informed lumped parameter model for near-surface underwater vehicle maneuvering," W. Lambert*, L. Miller, S. Brizzolara, and C. A. Woolsey, *Proc. MTS/IEEE OCEANS 2022*, Virginia Beach, VA, October 2022. [10.1109/OCEANS47191.2022.9976993]
- [65] "Passivity based cross-track control of a fixed-wing aircraft," J.-M. Fahmi and C. A. Woolsey, *CEAS Conf. on Guidance, Navigation and Control (EuroGNC)*, Berlin, Germany, May 2022.
- [66] "Quadditch: An augmented reality, multiplayer, aerial robotics game for outreach, education, and research," M. Foran, N. Nekoo, W. Foster, J.-M. Fahmi, N. Sakib, and C. A. Woolsey, CEAS Conf. on Guidance, Navigation and Control (EuroGNC), Berlin, Germany, May 2022.
- [67] "Flight test approach for modeling and nonlinear control validation for unmanned aircraft," J. Gresham*, J.-M. Fahmi*, B. Simmons*, W. Foster*, and C. A. Woolsey, AIAA SciTech Forum 2022, San Diego, CA, January 2022. [10.2514/6.2022-2406]
- [68] "Spin aerodynamic modeling for a fixed-wing aircraft using flight data," J. Gresham*, B. Simmons*, J. Hopwood*, and C. A. Woolsey, *AIAA SciTech Forum 2022*, San Diego, CA, January 2022. [10.2514/6.2022-1160]
- [69] "Wind estimation from an unsteady aerodynamic aircraft motion model," M. Halefom*, J. Gresham*, and C. A. Woolsey, *AIAA SciTech Forum 2022*, San Diego, CA, January 2022. [10.2514/6.2022-0554]
- "Stall spin flight path control using parallel yaw-periodic linear quadratic and robust H-infinity controllers,"
 J. Hopwood*, J. Gresham*, and C. A. Woolsey, *AIAA SciTech Forum 2022*, San Diego, CA, January 2022.
 [10.2514/6.2022-1159] Award: 2022 AIAA Atmospheric Flight Mechanics Best Student Paper
- [71] "Use of dynamic pose to enhance passive visual tracking," D. Marquis* and C. A. Woolsey, *AIAA SciTech Forum 2022*, San Diego, CA, January 2022. [10.2514/6.2022-1014]
- [72] "Aero-propulsive system identification for propeller-driven fixed-wing aircraft using flight data," B. Simmons*, J. Gresham*, and C. A. Woolsey, *AIAA SciTech Forum 2022*, San Diego, CA, January 2022. [10.2514/6.2022-2171]
- [73] "A heavy sphere in a vertical jet: A simple pedagogical demonstration of aerodynamics and stability," Z. Swartzwelder*, S. Woolsey*, and C. A. Woolsey, *AIAA AVIATION 2021*, June 2021. [10.2514/6.2021-2802]
- [74] "Optimal placement algorithm for multiple heterogeneous stereo vision systems," C. Kang* and C. A. Woolsey, *AIAA AVIATION 2021*, June 2021. [10.2514/6.2021-2393]
- [75] "Quantifying an equivalent level of safety for UAS shielded avoidance logic at low flight altitudes," K. Edmonds*, C. A. Woolsey, J. Coggin, and A. Kriz, *AIAA AVIATION 2021*, June 2021. [10.2514/6.2021-2316]

- [76] "Remote uncorrelated pilot inputs for nonlinear aerodynamic model identification from flight data," J. Gresham*, B. Simmons*, and C. A. Woolsey, *AIAA AVIATION 2021*, June 2021. [10.2514/6.2021-2792]
- [77] "Nonlinear, model-based disturbance estimation for fixed-wing aircraft," Y.-C. Chen* and C. Woolsey, *AIAA SciTech Forum 2021*, Virtual Conference, January 2021. [10.2514/6.2021-0018]
- [78] "Cross-track control of rotorcraft using passivity based techniques," J.-M. Fahmi* and C. Woolsey, *AIAA SciTech Forum 2021*, Virtual Conference, January 2021. [10.2514/6.2021-1991]
- [79] "A methodology to assess the re-purposing of manned aircraft airworthiness standards for unmanned aircraft," M. Halefom*, N. Sadab, A. Salado, and C. Woolsey, *AIAA SciTech Forum 2021*, Virtual Conference, January 2021. [10.2514/6.2021-1924]
- [80] "Usability studies of a heterogeneous stereo vision system in mitigating the effects of visual display delays," N. Sakib* and C. Woolsey, AIAA SciTech Forum 2021, Virtual Conference, January 2021. [10.2514/6.2021-0017]
- [81] "Development of a peripheral-central vision system for small UAS tracking," C. Kang*, H. Chaudhry, C. Woolsey, and K. Kochersberger, AIAA SciTech Forum 2019, San Diego, CA, January 2019. [10.2514/6.2019-2074]
- [82] "Effects of modeling assumptions on wind reconstruction during longitudinal flight," H. McClelland* and C. A. Woolsey, AIAA SciTech Forum 2019, San Diego, CA, January 2019. [10.2514/6.2019-1599] Award: 2019 AIAA Atmospheric Flight Mechanics Best Paper
- [83] "Model-based wind profiling in the lower atmosphere with multirotor UAS," J. González-Rocha*, C. A. Woolsey, C. Sultan, and S. F. J. De Wekker, *AIAA SciTech Forum 2019*, San Diego, CA, January 2019. [10.2514/6.2019-1598]
- [84] "Aerodynamic response of a NACA-0012 airfoil undergoing non-sinusoidal pitching waveforms," H. Shehata*, C. A. Woolsey, M. Zakaria, M. Hajj, *AIAA SciTech Forum 2019*, San Diego, CA, January 2019. [10.2514/6.2019-0303]
- [85] "A modular biolocomotion emulator for hydrodynamic testing in a towing tank," C. Beardsley*, L. Bergeron*, A. McLean*, K. Nguyen*, M. Vu*, C. Watson*, A. Nayfeh, H. Shehata, C. A. Woolsey, M. Hajj, *Proc. MTS/IEEE OCEANS 2018*, Charleston, SC, October 2018. [10.1109/OCEANS.2018.8604639]
- [86] "An immersed spheroidal pendulum oscillating near a free surface," B. Andersen, C. Beardsley, M. Gates, J. Schlafman, T. Battista, S. Jung, and C. A. Woolsey, *Proc. MTS/IEEE OCEANS 2018*, Charleston, SC, October 2018.[10.1109/OCEANS.2018.8604644]
- [87] "An analytical approximation of a force prediction model for a prolate spheroid moving at a constant forward speed parallel to a calm free surface," S. Jung, T. Battista, F. Valentinis, S. Brizzolara, E. Paterson, and C. Woolsey, *Proc. 13th Int. Conf. on Hydrodynamics*, Incheon, Korea, September 2018.
- [88] "Directional stabilization of a fixed-wing aircraft using potential shaping," J.-M. Fahmi* and C. A. Woolsey, *Proc. AIAA AVIATION*, Atlanta, GA, June 2018. [10.2514/6.2018-3620]
- [89] "Active flight path control for an induced spin flight termination system," P. Shukla* and C. A. Woolsey, *AIAA SciTech*, Orlando, FL, January 2018. [10.2514/6.2018-0528]
- [90] "Effects of depth on added mass obtained from virtual PMM tests of a submerged prolate spheroid," S. Jung*, T. Battista*, E. Paterson, and C. Woolsey, *Proc. MTS/IEEE OCEANS*, September 2017, Anchorage, AK. [INSPEC Accession Number: 17434535]
- [91] "Measuring atmospheric winds from quadrotor motion," J. González-Rocha*, C. A. Woolsey, C. Sultan, N. Rose, and S. F. J. De Wekker, AIAA SciTech Forum 2017, Grapevine, TX, January 2017. [10.2514/6.2017-1189]
- [92] "Small aircraft flight encounters database for UAS sense and avoid," H. G. McClelland*, C. K. Kang*, C. A. Woolsey, A. K. Roberts, D. Buck, T. Cheney, and K. F. Warnick, *AIAA SciTech Forum 2017*, Grapevine, TX, January 2017. [10.2514/6.2017-1152]
- [93] "Vibrational control of a 3-DOF damped mechanical system," S. Tahmasian, F. Jafari, & C. A. Woolsey, *Proc. Dynamic Systems and Control Conf.*, Minneapolis, MN, October 2016.
- [94] "Lift and drag of flapping membrane wings at high angles of attack," M. Zakaria, D. Allen, C. A. Woolsey, & M. Hajj, *AIAA AVIATION*, Washington, DC, June 2016. [10.2514/6.2016-3554]
- [95] "Assessing system safety for an urban, tethered UAS," L. E. Hale, C. Denham, R. Mooney, C. A. Woolsey, J. T. Luxhoj, & C. E. Mancini, *AIAA AVIATION*, Washington, DC, June 2016. [10.2514/6.2016-3595]

- [96] "Control of an underwater vehicle in irregular waves," T. Battista*, C. A. Woolsey, L. McCue-Weil, and E. Paterson. *Proc. MTS/IEEE OCEANS 2015*, Washington, DC, October 2015.
 [10.23919/OCEANS.2015.7401967]
- [97] "Testing a pneumatic underwater glider and acoustic ranging system in shallow water," A. Wolek*, T. Gode*, C. A. Woolsey, J. Quenzer, K. A. Morgansen. *Proc. MTS/IEEE OCEANS 2015*, Washington, DC, October 2015. [10.23919/OCEANS.2015.7401980]
- [98] "Design and demonstration of a flexible matrix composite actuated flap in a UAV," E. B. Doepke, M. Heim*, K. Pyne*, A. Bialy*, M. Burns*, G. Mohan*, N. Beaty*, C. MacNeal*, C. Weit*, C. Kevorkian*, C. A. Woolsey, and M. Philen, ASME 2015 Conference on Smart Materials, Adaptive Structures and Intelligent Systems (SMASIS), September 2015.
- [99] "A geometric control approach for the longitudinal flight stability of hovering insects/FWMAVs," H. Taha, C. A. Woolsey, and M. Hajj, *SciTech 2015*, Orlando FL, January 2015. [10.2514/6.2015-1552]
- [100] "Source localization for a turbulent plume model using Bayesian occupancy grid mapping," H. Abdelghaffar, C. A. Woolsey, and H. A. Ali, *SciTech 2015*, Orlando FL, January 2015. [10.2514/6.2015-1071]
- [101] "UAV source localization with high latency sensors in turbulent environments," M. Palframan* and C. A. Woolsey, *SciTech 2014*, National Harbor, MD, January 2014. [10.2514/6.2014-0605]
- [102] "Longitudinal flight control of flapping wing micro air vehicles," S. Tahmasian*, C. A. Woolsey, and H. Taha, *SciTech 2014*, National Harbor, MD, January 2014. [10.2514/6.2014-1470]
- [103] "Flight testing of a subscale aeroservoelastic aircraft," J. Oullette, M. Patil, and C. A. Woolsey, *SciTech 2014*, National Harbor, MD, January 2014. (Best Paper Award for Atmospheric Flight Mechanics.) [10.2514/6.2014-0032]
- [104] "Design and implementation of aerobiological sampling system for real-time detection with a surface plasmon resonance equipped UAV," M. Palframan*, H. A. Gruszewski, D. Schmale, and C. A. Woolsey, *Infotech@Aerospace 2013*, Boston, MA, August 2013. [10.2514/6.2013-4670]
- [105] "Design and evaluation of geometric nonlinearities using 5 meter Joined-Wing SensorCraft flight test article," J. Richards, J. Garnand-Royo*, A. Suleman, R. Canfield, C. A. Woolsey, *Structures, Structural Dynamics, and Materials Conference*, April 8-11, 2013, Boston, MA.
- [106] "Geometric control of a flapping device in a uniform flow," H. Taha, C. Woolsey and S. Tahmasian, *AIAA Aerospace Sciences Meeting*, January 7-10, 2013, Dallas, TX. [10.2514/6.2013-768]
- [107] "A maneuverable pneumatic underwater glider" A. Wolek*, J. Burns*, C. A. Woolsey, J. Quenzer, L. Techy, and K. Morgansen. *Proc. MTS/IEEE OCEANS 2012*, October 14-19, 2012, Virginia Beach, VA. [10.1109/OCEANS.2012.6404989]
- [108] "Stability and performance of underwater gliders" S. Fan, A. Nguyen*OCEANS 2012*, October 14-19, 2012, Virginia Beach, VA. [10.1109/OCEANS.2012.6404993]
- [109] "An experimental comparison of USV trajectory tracking control laws" C. Sonnenburg and C. A. Woolsey. *Proc. MTS/IEEE OCEANS 2012*, October 14-19, 2012, Virginia Beach, VA. [10.1109/OCEANS.2012.6404999]
- [110] "Guidance and control of an unmanned surface vehicle exhibiting sternward motion" A. Gadre, S. Du, C. Sonnenburg, D. J. Stilwell, and C. A. Woolsey. *Proc. MTS/IEEE OCEANS 2012*, October 14-19, 2012, Virginia Beach, VA. [10.1109/OCEANS.2012.6405021]
- [111] "LQR controller for stabilization of flapping wing MAV in gust environments," M. Bhatia, M. Patil, and C. A. Woolsey, 2012 AIAA Atmospheric Flight Mechanics Conference, Minneapolis, MN, August 2012.
 [10.2514/6.2012-4867]
- [112] "Airworthiness evaluation of a scaled joined-wing aircraft," J. Richards, T.Aarons, J. Garnand-Royo*, A. Suleman, R. A. Canfield, and C. A. Woolsey, *Structures, Structural Dynamics, and Materials Conference*, Honolulu, HI, April 2012. [10.2514/6.2012-1721]
- [113] "Design for flight test of a scaled joined wing SensorCraft," J. Richards, T. Aarons*, A. Suleman, R. A. Canfield, C. Woolsey, N. Lindsley, and M. Blair, *Structures, Structural Dynamics, and Materials Conference*, Denver, CO, April 2011. [10.2514/6.2011-2011]
- [114] "Control-oriented planar motion modeling of unmanned surface vehicles," C. Sonnenburg*, A. Gadre, D. Horner, S. Kragelund, D. J. Stilwell, and C. A. Woolsey, *MTS/IEEE OCEANS 2010*, Seattle, WA [10.1109/OCEANS.2010.5664297]

- [115] "Developmental flight testing of the SPAARO UAV," M. C. Cotting, A. Wolek, J. F. Murtha, and C. A. Woolsey, 48th AIAA Aerospace Sciences Meeting and Exposition, Orlando, FL, January 2010.
 [10.2514/6.2010-295]
- [116] "Monitoring the spread of a plant pathogen in the lower atmosphere using unmanned aerial vehicles and a buoyancy-controlled weather balloon," L. Techy, D. Schmale, & C. Woolsey, *SAE AeroTech Congress & Exhibition*, Seattle, WA, October 2009. [10.4271/2009-01-3125]
- [117] "Optimal underwater glider trajectories in depth-varying currents," R. J. Kraus, C. A. Woolsey, and E. M. Cliff. *Proc.* 2009 Int. Symp. on Unmanned Untethered Submersible Technology, Durham, NH, August 2009.
- [118] "Underwater glider path planning for efficient oceanographic sampling," N. Mahmoudian and C. A. Woolsey. *Proc. 2009 Int. Symp. on Unmanned Untethered Submersible Technology, Durham, NH, August 2009.*
- [119] "Subsurface and surface sensing for autonomous navigation in a riverine environment," A. Gadre, S. Kragelund, T. Masek, D. Stilwell, C. A. Woolsey, and D. Horner. *Proc. AUVSI Unmanned Systems North America*, August 10-13. 2009, Washington, DC
- [120] "The educational impact of creating a new UAV for curriculum enhancement," J. F. Murtha*, M. C. Cotting*, A. Wolek*, T. Aarons*, and C. A. Woolsey, 2009 AIAA Atmospheric Flight Mechanics Conference, Chicago, IL, August 2009. (AIAA-2009-5851) [10.2514/6.2009-5851]
- [121] "Examples of augmentation of an atmospheric flight mechanics curriculum using UAVs," M. C. Cotting*, J. F. Murtha*, L. Techy*, and C. A. Woolsey, 2009 AIAA Atmospheric Flight Mechanics Conference, Chicago, IL, August 2009. (AIAA 2009 5852) [10.2514/6.2009-5852]
- [122] "Coordinated perimeter patrol with minimum-time alert response," D. Paley, L. Techy* and C. A. Woolsey, *AIAA Guidance, Navigation, and Control Conference*, Chicago, IL, August 2009. (Invited paper; AIAA-2009-6210) [10.2514/6.2009-6210]
- [123] "Analysis of feedforward-feedback control design for underwater gliders based on slowly varying systems theory," N. Mahmoudian* and C. A. Woolsey, *AIAA Guidance, Navigation, and Control Conference*, Chicago, IL, August 2009. (AIAA-2009-5755) [10.2514/6.2009-5755]
- [124] "Trajectory tracking for high aspect-ratio flying wings," B. Raghavan, M. J. Patil, and C. A. Woolsey, 2008 AIAA Atmospheric Flight Mechanics Conference, Honolulu, HI, August 2008 (AIAA-2008-6372) [10.2514/6.2008-6372]
- [125] "Steady turns and optimal paths for underwater gliders," N. Mahmoudian*, J. Geisbert*, and C. A. Woolsey, *AIAA Guidance, Navigation, and Control Conference*, Hilton Head Island, SC, August 2007 (AIAA-2007-6602) [10.2514/6.2007-6602]
- [126] "Ground target localization and tracking in a riverine environment from a UAV with a gimbaled camera," M. J. Monda*, C. A. Woolsey, and C. K. Reddy*, *AIAA Guidance, Navigation, and Control Conference*, Hilton Head Island, SC, August 2007 (AIAA-2007-6747) [10.2514/6.2007-6747]
- [127] "Rapid motion estimation of a target moving with time-varying velocity," V. N. Dobrokhodov, I. I. Kaminer, K. D. Jones, I. Kitsios, C. Cao, L. Ma*, N. Hovakimyan, and C. A. Woolsey, *AIAA Guidance, Navigation, and Control Conference*, Hilton Head Island, SC, August 2007 (AIAA-2007-6746) [10.2514/6.2007-6746]
- [128] "Development of a vision-based guidance law for tracking a moving target," L. Ma*, C. Cao, N. Hovakimyan, C. A. Woolsey, V. N. Dobrokhodov, and I. I. Kaminer, *AIAA Guidance, Navigation, and Control Conference*, Hilton Head Island, SC, August 2007 (AIAA-2007-6744) [10.2514/6.2007-6744]
- [129] "Flight test bed for visual tracking of small UAVs," L. Ma*, V. Stepanyan, C. Cao, I. Faruque*, C. A. Woolsey, and N. Hovakimyan. *Proc. 2006 AIAA Guidance, Navigation, and Control Conference*, Aug. 21-24, Keystone, CO. (AIAA-2006-6609) [10.2514/6.2006-6609]
- [130] "Identification of a low-complexity flow field model for AUV applications," J. Petrich*, C. A. Woolsey, and D. J. Stilwell. *Proc. MTS/IEEE OCEANS 2005*, September 19-23, 2005, Washington, DC [10.1109/OCEANS.2005.1639984]
- [131] "A low-speed control module for a streamlined AUV," C. Nickell*, C. A. Woolsey, and D. J. Stilwell. *Proc. MTS/IEEE OCEANS 2005*, September 19-23, 2005, Washington, DC [10.1109/OCEANS.2005.1639997]
- [132] "Design and simulation of a two stage towing system," E. Schuch*, A. Linklater*, N. Lambeth*, and C. A. Woolsey. *Proc. MTS/IEEE OCEANS 2005*, September 19-23, 2005, Washington, DC [10.1109/OCEANS.2005.1640001]
- [133] "Adaptive output feedback control of a spheroidal underactuated underwater vehicle," V. Stepanyan, N. Hovakimyan, and C. A. Woolsey. *Proc. MTS/IEEE OCEANS 2005*, September 19-23, 2005, Washington, DC [10.1109/OCEANS.2005.1639776]

- [134] "Model-based nonlinear control of an SMA-actuated robotic arm," M. H. Elahinia, J. Koo, C. Woolsey and M. Ahmadian. ASME International Mechanical Engineering Congress, November 13-19, 2004, Anaheim, CA.
- [135] "Model-based nonlinear control of an SMA-actuated robotic arm: An experimental study," J. Koo, M. H. Elahinia, M. Ahmadian, and C. Woolsey. *Tenth Conference on Nonlinear Vibrations, Stability, and Dynamics of Structures*, July 25-29, 2004, Blacksburg, VA.
- [136] "An experimental platform for validating internal actuator control strategies," C. Schultz* and C. Woolsey. *Proc. Ist IFAC Workshop on Guidance & Control of Underwater Vehicles*, pp. 209-214, Newport, South Wales, U.K. 2003. [10.1016/S1474-6670(17)36682-X]
- [137] "Assessing conceptual knowledge in an engineering course: Four case studies," M. Allen, W. Devenport, J. Wang, and C. Woolsey. AIAA Paper 2003-949, *Proc.* 41st AIAA Aerospace Sciences Meeting. [10.2514/6.2003-949]

<u>Ph.D. Dissertation:</u> Energy Shaping and Dissipation: Underwater Vehicle Stabilization Using Internal Rotors, Craig Woolsey, Princeton University, December 2000. (Doctoral Advisor: Naomi Leonard)

Externally Sponsored Research:

Summary of External Research Funding

	<u> </u>	
Number of Projects	Total Amount	Woolsey Component
58	\$22,664,603	\$8,279,460

Projects directed by C. Woolsey (reverse chronological order by end date)

[1] Proposal Title: AF21B-T003 Restricted SWAP-C Air Direction Sensing to Enable Single Vehicle Chemical

Reactive Tracking: Phase II

Principal Investigator: C. Woolsey

Period of Performance: April 19, 2023 – April 18, 2025

Sponsor: Barron Associates, Inc. (AFRL)

Amount: \$225,000

Woolsey Component: \$225,000 (100%)

[2] Proposal Title: A23B-T009 Small Unmanned Aerial System for Surveying the Electromagnetic Spectrum:

Phase I

Principal Investigator: C. Woolsey

Period of Performance: October 1, 2023 – March 31, 2024

Sponsor: Sabre Systems, Inc. (NAVAIR)

Amount: \$70,000

Woolsey Component: \$70,000 (100%)

[3] Proposal Title: Bayesian Localization of Multiple Atmospheric Contaminant Sources

Principal Investigator: C. Woolsey

Period of Performance: January 1, 2022 – June 30, 2023

Sponsor: C2IAS Amount: \$46,234

Woolsey Component: \$46,234 (100%)

[4] Proposal Title: AF21B-T003 Restricted SWAP-C Air Direction Sensing to Enable Single Vehicle Chemical

Reactive Tracking: Phase I

Principal Investigator: C. Woolsey

Period of Performance: January 30, 2022 – October 20, 2022

Sponsor: Barron Associates, Inc. (AFRL)

Amount: \$30,000

Woolsey Component: \$30,000 (100%)

[5] **Proposal Title:** Wind Sensing From UAVs

Principal Investigator: C. Woolsey

Period of Performance: October 21, 2021 to January 31, 2022

Sponsor: NIA (NASA LaRC flowthrough)

Amount: \$13,074

Woolsey Component: \$13,074 (100%)

[6] **Proposal Title:** Classification Scheme for Multirotor Aircraft

Principal Investigator: C. Woolsey

Period of Performance: February 1, 2021 to July 31, 2021 **Sponsor:** Perspecta Labs (CCDC Armaments Center)

Amount: \$70,000

Woolsey Component: \$70,000 (100%)

[7] Proposal Title: Real-time Weather Awareness for Enhanced UTM Safety Assurance

Principal Investigator: C. Woolsey

Period of Performance: August 1, 2020 to July 31, 2024 **Sponsor:** NASA (via Oklahoma State University)

Amount: \$600,000

Woolsey Component: \$600,000 (100%)

[8] Proposal Title: eSPAARO UAS Project for USAF TPS/AF

Principal Investigator: C. Woolsey

Period of Performance: August 16, 2019 to August 15, 2021

Sponsor: USAF Test Pilot School

Amount: \$220,000

Woolsey Component: \$220,000 (100%)

[9] Proposal Title: FW-HTF: First Person View and Augmented Reality for Airborne Embodied Intelligent

Cognitive Assistants

Principal Investigator: J. Gabbard, M. Hebdon, P. Tokekar, and C. Woolsey (Lead) **Period of Performance:** September 1, 2018 to August 31, 2021 2022 (No-cost extension)

Sponsor: National Science Foundation

Amount: \$1,500,000

Woolsey Component: \$375,000 (25%)

[10] **Proposal Title:** Submarine Motion in Waves

Principal Investigator: E. Paterson and C. Woolsey (Lead)

Period of Performance: July 1, 2016 to June 30, 2019 2020 (No-cost extension)

Sponsor: Office of Naval Research

Amount: \$395,584

Woolsey Component: \$197,792 (50%)

[11] Proposal Title: Collaborative Research: Unsteady Hydrodynamics and Geometric Control of Pisciform

Locomotion

Principal Investigator: M. Hajj and C. Woolsey (Lead)

Period of Performance: September 1, 2016 to August 31, 2019 2020 (No-cost extension)

Sponsor: National Science Foundation

Amount: \$270,000

Woolsey Component: \$135,000 (50%)

[12] **Proposal Title:** I/UCRC: Center for UAS Phase II Site: Virginia Tech **Principal Investigator:** K. Kochersberger and C. Woolsey (Lead)

Period of Performance: March 1, 2017 to February 2022

Sponsor: National Science Foundation

Amount: \$500,000

Woolsey Component*: \$250,000 (50%)

Note: Virginia Tech Site within an existing NSF I/UCRC established by BYU and CU-Boulder. This Phase II site supersedes a Phase I site which ended with the original Phase I grant to BYU and CU-Boulder. Funds from

NSF are supplemented by membership fees from industry/government members of the C-UAS. Industry membership fees of \$44,000/Year per member support a varying roster of investigators and projects. *Member fee contributions through 2020 total \$1.7M*. Funding totals above account only for direct NSF sponsorship.

[13] Proposal Title: I/UCRC: Center for UAS Phase I Site

Principal Investigator: K. Kochersberger and C. Woolsey (Lead) **Period of Performance:** September 1, 2015 to August 31, 2020 2018

Sponsor: National Science Foundation

Amount: \$324,996 \$130,000

Woolsey Component*: \$162,498 \$65,000 (50%)

Note: Phase I industry membership fees of \$40,000/Year per member supported a varying roster of investigators and projects. Member fee contributions range from \$200,000 to \$300,000 annually, but funding totals reported here *do not account for member-sponsored research tasks*.

[14] **Proposal Title:** Planning Grant: I/UCRC Center for UAS Site Addition **Principal Investigator:** K. Kochersberger and C. Woolsey (Lead) **Period of Performance:** February 10, 2015 to February 29, 2016

Sponsor: National Science Foundation

Amount: \$10,000

Woolsey Component: \$5000 (50%)

[15] Proposal Title: Motion Prediction & Control for Submarines in High Sea States: The Virginia Tech

Component of an International Collaboration

Principal Investigator: L. McCue-Weil, E. Paterson, and C. Woolsey (Lead)

Period of Performance: June 1, 2014 to May 31, 2017

Sponsor: Office of Naval Research

Amount: \$590,229

Woolsey Component: \$200,668 (34%)

Note: Project coordinated with investigators at DSTO and Queensland University of Technology

[16] **Proposal Title:** Hybrid UA/UV: Support for Barron Associates

Principal Investigator: E. Paterson, D. Stilwell, and C. Woolsey (Lead)

Period of Performance: July 1, 2016 to January 31, 2017

Sponsor: Barron Associates (Office of Naval Research SBIR Flow-through)

Amount: \$24,000

Woolsey Component: \$8,000 (34%)

[17] Proposal Title: Biolocomotion Analysis and Design Using Geometric Control and Averaging Methods

Principal Investigator: M. Hajj and C. Woolsey (Lead)

Period of Performance: September 1, 2014 to August 31, 2016

Sponsor: National Science Foundation

Amount: \$350,000

Woolsey Component: \$175,000 (50%)

[18] **Proposal Title:** Underwater Gliders in Significant Currents

Principal Investigator: C. Woolsey

Period of Performance: December 26, 2012 to October 31, 2014

Sponsor: Office of Naval Research

Amount: \$194,975

[19] **Proposal Title:** Ultra-Efficient Transport Aircraft

Principal Investigator: C. Woolsey

Period of Performance: August 10, 2012 to August 9, 2014

Sponsor: National Institute of Aerospace

Amount: \$71,837

Note: Project coordinated with Mr. M. D. Guynn (NASA Langley Research Center)

[20] **Proposal Title:** Autonomous Systems Technology, Economics, & Policy Survey

Principal Investigator: T. Campbell, J. Greene, J. Shand, and C. Woolsey (Lead)

Period of Performance: October 1, 2013 to May 14, 2014

Sponsor: Virginia Department of Aviation

Amount: \$139,798

Woolsey Component: \$90,958 (65%)

[21] **Proposal Title:** Additional Support for Impact/Sikorsky ASPEC Program

Principal Investigator: C. Woolsey

Period of Performance: January 1, 2013 to July 31, 2013

Sponsor: Sikorsky, formerly Impact Technologies (NUWC-Newport flowthrough)

Amount: \$56,657

Woolsey Component: \$19,263 (34%)

[22] Proposal Title: Support for "A Propulsion-Enabled Control System for Precise Submarine Maneuvering"

Principal Investigators: W. Neu, D. Stilwell, and C. Woolsey (Lead)

Period of Performance: April 1, 2011 to January 30, 2013 **Sponsor:** Impact Technologies (NUWC-Newport flowthrough)

Amount: \$180,000

Woolsey Component: \$60,000 (33%)

[23] Proposal Title: Efficient Motion Control for Undersea Gliders: Experimental Implementation and Assessment

Principal Investigator: C. Woolsey

Period of Performance: January 1, 2011 to December 31, 2012

Sponsor: Office of Naval Research

Amount: \$209,929

Note: Project coordinated with Dr. K. Morgansen (U. Washington)

[24] Proposal Title: Marine and Hydrokinetic Technology: Support for THOR, LLC

Principal Investigators: C. Woolsey

Period of Performance: January 1, 2011 to December 31, 2011 **Sponsor:** Turner Hunt Ocean Renewable (DOE flowthrough)

Amount: \$60,213

[25] Proposal Title: Efficient Motion Control for Undersea Gliders: Implementation and Assessment Using

Seaglider

Principal Investigators: E. Cliff and C. Woolsey (Lead)

Period of Performance: September 1, 2009 to December 31, 2010

Sponsor: Office of Naval Research

Amount: \$55,039

Woolsey Component: \$27,520 (50%)

Note: Project coordinated with Dr. K. Morgansen (U. Washington)

[26] **Proposal Title:** UAV Flying Qualities Criteria Development and Evaluation

Principal Investigators: W. Durham and C. Woolsey (Lead) **Period of Performance:** July 1, 2008 to September 30, 2010

Sponsor: Naval Air Warfare Center (NAVAIR)

Amount: \$166,450

Woolsey Component: \$83,225 (50%)

[27] Proposal Title: Evidence Based Approach to Improved Small UAV Reliability

Principal Investigators: J. Marchman and C. Woolsey (Lead) **Period of Performance:** July 1, 2008 to December 10, 2009

Sponsor: Naval Air Warfare Center (NAVAIR)

Amount: \$134,673

Woolsey Component: \$67,337 (50%)

[28] **Proposal Title:** Motion Planning for Underwater Gliders **Principal Investigators:** E. Cliff and C. Woolsey (Lead)

Period of Performance: October 1, 2007 to September 30, 2009

Sponsor: Office of Naval Research

Amount: \$213,044

Woolsey Component: \$174,696 (82%)

[29] Proposal Title: In-Flight Data Collection Using a N~ASK Transponder

Principal Investigators: C. Woolsey

Period of Performance: January 1, 2009 to August 15, 2009

Sponsor: N~ASK, Inc. **Amount:** \$33,928

Woolsey Component: \$33,928 (100%)

[30] **Proposal Title:** Internally actuated lateral-directional maneuvering for a blended wing-body underwater glider

Principal Investigators: C. Woolsey

Period of Performance: May 15, 2005 to December 31, 2007

Sponsor: Office of Naval Research

Amount: \$259,688

Woolsey Component: \$259,688 (100%)

[31] Proposal Title: CAREER: Internal shape control for ocean and atmospheric vehicles (NSF Faculty Early

Career Development Award)

Principal Investigators: C. Woolsey

Period of Performance: May 1, 2002 to April 30, 2007

Sponsor: National Science Foundation

Amount: \$381,000

Woolsey Component: \$381,000 (100%)

[32] **Proposal Title:** Fleet applications of AUVs: A technology development roadmap

Principal Investigators: W. Neu, D. Stilwell, and C. Woolsey (Lead)

Period of Performance: May 15, 2006 to December 31, 2006

Sponsor: Office of Naval Research

Amount: \$27,694

Woolsey Component: \$9416 (34%)

[33] Proposal Title: Heterogeneous teams of autonomous vehicles: Advanced sensing and control

Principal Investigators: D. Hong, N. Hovakimyan, M. Johnson, C. Reinholtz, D. Stilwell, A. Wicks, C.

Woolsey (Lead), C. Wyatt

Period of Performance: July 1, 2005 to June 30, 2006

Sponsor: Office of Naval Research

Amount: \$1,050,000

Woolsey Component: \$180,712 (17%)

Note: Project coordinated with investigators at Naval Postgraduate School

[34] Proposal Title: Collaborative Research: A two-stage towing system for swath-mapping ocean turbulence

Principal Investigator: C. Woolsey

Period of Performance: August 16, 2002 to August 15, 2005

Sponsor: National Science Foundation

Amount: \$217,936

Woolsey Component: \$217,936 (100%)

Note: Project coordinated with Dr. A. Gargett (Old Dominion U.)

[35] **Proposal Title:** Real-time flow-field estimation for cooperative autonomous underwater vehicle mission

planning (Supplement to YIP Award to support collaboration with a U.S. Navy laboratory.)

Principal Investigators: C. Woolsey

Period of Performance: June 1, 2004 to June 30, 2005

Sponsor: Office of Naval Research

Amount: \$50,000

Woolsey Component: \$50,000 (100%)

[36] Proposal Title: Low velocity attitude control for underwater vehicles using internal actuators (ONR Young

Investigator Program Award) **Principal Investigators:**

Period of Performance: May 1, 2002 to April 30, 2005

Sponsor: Office of Naval Research

Amount: \$300,000

Woolsey Component: \$300,000 (100%)

[37] Proposal Title: A self-sustaining, boundary-layer-adapted system for terrain exploration and environmental

sampling

Principal Investigators: G. Hagerman, C. Woolsey (Lead) **Period of Performance:** October 1, 2004 to March 31, 2005

Sponsor: NASA Institute for Advanced Concepts

Amount: \$69,513

Woolsey Component: \$47,424 (66%)

Projects directed by collaborators (reverse chronological order by end date)

[38] Proposal Title: I/UCRC: Center for Autonomous Air Mobility and Sensing: Virginia Tech

Principal Investigator: K. Kochersberger (Lead) and C. Woolsey

Period of Performance: March 2022 to February 2027

Sponsor: National Science Foundation

Amount: \$506,628

Woolsey Component*: \$253,314 (50%)

Note: Virginia Tech Site within a 6-university NSF Phase I I/UCRC. Funds from NSF are supplemented by membership fees from industry/government members of the C-UAS. Industry membership fees of \$50,000/Year per member support a varying roster of investigators and projects. The funding amounts shown above account only for direct NSF sponsorship.

[39] Proposal Title: Identification and validation of a Lagrangian nonlinear maneuvering and seakeeping model

Principal Investigator: S. Brizzolara (PI) and C. Woolsey **Period of Performance:** June 1, 2020 to May 31, 2023

Sponsor: Office of Naval Research

Amount: \$577,637

Woolsey Component: \$288,818 (50%)

[40] **Proposal Title:** Omniscient Planning and Control Environment for the Naval Enterprise **Principal Investigator:** D. Stilwell (PI), E. Paterson, M. Farhood, and C. Woolsey

Period of Performance: June 25, 2018 to September 30, 2020 December 31, 2022 (No-cost extension)

Sponsor: Office of Naval Research

Amount: \$3,000,000

Woolsey Component: \$750,000 (25%)

[41] Proposal Title: Advanced towing carriage and instrumentation for the study of small vessels in waves

Principal Investigator: C. Gilbert (PI) and C. Woolsey **Period of Performance:** June 15, 2018 to June 14, 2019

Sponsor: Office of Naval Research

Amount: \$620,057

Woolsey Component: \$310,028 (50%)

[42] **Proposal Title:** Structure-preserving numerical methods for engineering applications

Principal Investigators: M. Patil (Lead) and C. Woolsey **Period of Performance:** July 1, 2018 to July 31, 2020

Sponsor: Office of Naval Research

Amount: \$220,059

Woolsey Component: \$110,030 (50%)

[43] Proposal Title: Hazards SEES: Uncovering the hidden skeleton of environmental flows: Advanced

Lagrangian methods for hazards prediction, mitigation and response*

Principal Investigator: S. Ross (Sub-Award PI), D. Schmale, III (Key Person), and C. Woolsey (Key Person)

Period of Performance: September 1, 2015 to August 31, 2019

Sponsor: National Science Foundation

Amount: \$514,192

Woolsey Component: \$128,117 (25%)

*Note: Virginia Tech component of \$3M award to Thomas Peacock (PI) and Co-PI's Pierre Lermusiaux,

Shane Ross, Irina Rypina, and Shawn Shadden

[44] **Proposal Title:** Virginia Tech Airworthiness Center

Principal Investigators: R. Canfield (PI) M. Farhood, K. Lowe, L. McCue, C. Sultan, and C. Woolsey

Period of Performance: January 15, 2015 to June 2, 2016

Sponsor: NAVAIR **Amount:** \$519,950

Woolsey Component: \$83,192 (16%)

[45] **Proposal Title:** UAS in the NAS

Principal Investigators: R. Mooney (PI) and C. Woolsey

Period of Performance: January 15, 2015 to December 31, 2015

Sponsor: Northrop Grumman – Information Systems

Amount: \$95,000

Woolsey Component: \$47,500 (50%)

[46] **Proposal Title:** THOR: Tactical Hazardous Operations Robot (Phase 1)

Principal Investigators: D. Hong and C. Woolsey

Period of Performance: October 1, 2012 to December 21, 2013

Sponsor: DARPA **Amount:** \$2,999,968

Woolsey Component: \$60,000 (2%)

[47] Proposal Title: AFRL-VT Collaborative Center On Multidisciplinary Analysis And Design Of Future

Aerospace Vehicles

Principal Investigators: R. Batra, R. Canfield, M. Hajj, R. Kapania (Lead), W. Mason, M. Patil, D. Tafti, L.

Watson, and C. Woolsey

Period of Performance: December 22, 2008 to December 21, 2013

Sponsor: Air Force Research Laboratory, WPAFB

Amount: \$1,595,028

Woolsey Component: \$79,751 (5%)

[48] **Proposal Title:** Exploration of Under-ice Regions with Ocean Profiling Agents (EUROPA)

Principal Investigators: L. McCue (Lead) and C. Woolsey Period of Performance: August 15, 2012 to August 14, 2013 Sponsor: National Institute for Aerospace (NIAC flowthrough)

Amount: \$53,977

Woolsey Component: \$21,590 (40%)

Note: Project coordinated with investigators at Naval Postgraduate School

[49] **Proposal Title:** Sensing and Autonomy for Riverine Vessels **Principal Investigators:** D. Stilwell (Lead) and C. Woolsey

Period of Performance: January 1, 2012 to September 30, 2012

Sponsor: Office of Naval Research

Amount: \$119,493

Woolsey Component: \$29,873 (25%)

Note: Project coordinated with investigators at Naval Postgraduate School

[50] **Proposal Title:** Sensing and Autonomy for Riverine Vessels

Principal Investigators: M. Patil (Lead) and C. Woolsey **Period of Performance:** June 1, 2011 to December 31, 2011

Sponsor: Office of Naval Research

Amount: \$60,000

Woolsey Component: \$27,000 (45%)

[51] Proposal Title: A Hardware Testbed for Distributed Learning, Estimation and Approximation Theory with

Sensor Vehicle Networks

Principal Investigators: A. Kurdila (Lead), A. Leonessa, D. Stilwell, C. Woolsey

Period of Performance: June 15, 2010 to June 14, 2011

Sponsor: Army Research Office

Amount: \$441,970

Woolsey Component: \$110,493 (25%)

[52] Proposal Title: Enhanced Riverine Drifter

Principal Investigators: P. Diplas, D. Stilwell (Lead), and C. Woolsey

Period of Performance: July 1, 2010 to April 30, 2011 **Sponsor:** Barron Associates (ONR flowthrough)

Amount: \$49,966

Woolsey Component: \$16,655 (25%)

[53] **Proposal Title:** Autonomous USV Navigation in Riverine Environments

Principal Investigators: D. Stilwell (Lead) and C. Woolsey **Period of Performance:** September 1, 2009 to December 31, 2010

Sponsor: Office of Naval Research

Amount: \$259,969

Woolsey Component: \$129,985 (50%)

Note: Project coordinated with investigators at Naval Postgraduate School

[54] Proposal Title: Experimental Scale Underwater Glider

Principal Investigators: L. McCue-Weil (Lead) and C. Woolsey **Period of Performance:** May 6, 2010 to September 30, 2010

Sponsor: University of Michigan (Naval Engineering Education Consortium)

Amount: \$69,348

Woolsey Component: \$34,674 (50%)

[55] **Proposal Title:** USV Autonomy in Riverine Environments **Principal Investigators:** D. Stilwell (Lead) and C. Woolsey

Period of Performance: May 1, 2008 to December 31, 2009

Sponsor: Office of Naval Research

Amount: \$381,757

Woolsev Component: \$190,879 (50%)

Note: Project coordinated with investigators at Naval Postgraduate School

[56] Proposal Title: Design and Prototype Development of a Flight Vehicle for Large Event Surveillance

Principal Investigators: J. Marchman (Lead) and C. Woolsey **Period of Performance:** August 1, 2007 to October 31, 2009

Sponsor: Virginia Space Grant Consortium (flow-through from NAVAIR)

Amount: \$143.533

Woolsey Component: \$71,767 (50%)

[57] **Proposal Title:** Coordinated sensing and control for surveillance and tracking by heterogeneous autonomous vehicle teams.

Principal Investigators: N. Hovakimyan, A. Kurdila, M. Roan, C. Reinholtz, D. Stilwell (Lead), A. Wicks, C.

Woolsey, C. Wyatt

Period of Performance: October 1, 2006 to September 30, 2007

Sponsor: Office of Naval Research

Amount: \$1,417,500

Woolsey Component: \$226,000 (16%)

Note: Project coordinated with investigators at Naval Postgraduate School

[58] **Proposal Title:** Adaptive sampling in dynamic environments using AUVs

Principal Investigators: D. Stilwell (Lead), C. Woolsey **Period of Performance:** May 30, 2005 to May 29, 2006

Sponsor: Office of Naval Research

Amount: \$479,750

Woolsey Component: \$86,969 (18%)

Note: Project coordinated with investigators at Tulane University

Courses Taught:3

AOE 3034: System Dynamics and Control

AOE 3104: Aircraft Performance

AOE 3134: Air Vehicle Dynamics

AOE 3234: Ocean Vehicle Dynamics

AOE 4004: State-Space Control

AOE 4224/5224G: Atmospheric & Ocean Vehicle Model Identification

AOE 4804: Special Topics in Dynamics, Control, and Estimation: Ethics and Autonomy

AOE 4984 (Special Topics): Navigation and Guidance

AOE 5774: Nonlinear Systems Theory

AOE 6744: Linear Control Theory

AOE 5984 (Special Topics): Real-time Control (Co-taught with Prof. Chris Hall)

AOE 6984 (Special Topics): Geometric Control Theory (Co-taught with Prof. Andy Kurdila)

Advising:

Post-Doctoral Scholars

Current:

None

Complete:

Dr. Ahmed Hussein

Dr. Hye-Young Kim

Co-advised with Dr. M. Hajj

Co-advised with Dr. C. Hall

Dr. C. Konda Reddy
Co-advised with Dr. N. Hovakimyan
Dr. Lili Ma
Co-advised with Dr. N. Hovakimyan

Dr. Sevak Tahmasian Sole Advisor

Graduate Scholars (Ph.D. Candidates)

Current.

Garrett Asper (Ph.D. A.E., expected 2028)

Jeremy Hopwood (Ph.D. A.E., expected 2025)

Ian Willebeek-LeMair (Ph.D. A.E. expected 2027)

Sole Advisor

Sole Advisor

Mohamed Zakaria (Ph.D. A.E. expected 2025) Co-Advisor (with Dr. S. Ross)

Complete:

Chris Gahan (Ph.D. A.E., 2024)

Zakia Ahmed (Ph.D. M.E., 2024)

Mekonen Halefom (Ph.D. A.E., 2024)

Nazmus Sakib (Ph.D. A.E., 2024)

Sole Advisor

Ying-Chun Chen (Ph.D., A.E. 2023)

Lione Lambort (Ph.D. A.E. 2023)

Sole Advisor

Liam Lambert (Ph.D. A.E., 2023) Secondary Advisor (with Dr. S. Brizzolara) Ben Simmons (Ph.D. A.E., 2023) Primary Advisor (with Dr. E. Morelli)

Jean-Michel Fahmi (Ph.D. A.E., 2022) Sole Advisor

³ The teaching requirement in Virginia Tech's Department of Aerospace & Ocean Engineering is 3 courses per year.

James Gresham (Ph.D. A.E., 2022)

Emmanuel Skamangas (Ph.D. A.E., 2021) Javier González-Rocha (Ph.D. A.E., 2020)

Seyong Jung (Ph.D. A.E., 2020) Changkoo Kang (Ph.D. A.E., 2020) Harsh Sharma (Ph.D. A.E., 2020) Hisham Shehata (Ph.D. E.S.M., 2020) Hunter McClelland (Ph.D. A.E., 2019)

Tom Battista (Ph.D. A.E., 2018) Jacob Bean (PhD. A.E., 2018) David Allen (Ph.D. A.E., 2016) Andrew Rogers (Ph.D. A.E., 2016) Sevak Tahmasian (Ph.D. E.S.M., 2015)

Artur Wolek (Ph.D. A.E., 2015) Brad Atkins (Ph.D. A.E., 2014)

Christian Sonnenburg (Ph.D. A.E., 2012) Chris Cotting (Ph.D. A.E., 2010)

Robert Kraus (Ph.D. A.E., 2010) Amanda Young Dippold (Ph.D. A.E., 2009)

Nina Mahmoudian (Ph.D. A.E., 2009) Laszlo Techy (Ph.D. A.E., 2009)

Chevva Konda Reddy (Ph.D. E.S.M., 2005)

Graduate Scholars (M.S. Candidates, Thesis Option)

Current:

Patrick Corrigan (M.S. A.E., expected 2026) Genevieve Petsopoulos (M.S. A.E., expected 2025)

Sam Widman (M.S. A.E., expected 2026)

Complete:

Zakia Ahmed (M.S. M.E., 2022)

Ryan Fisher (M.S. A.E., 2022)

Sole Advisor

Sole Advisor

Kendy Edmonds (M.S. A.E., 2021) Primary Advisor (with Mr. John Coggin)

Khanh Nguyen (M.S. A.E., 2021)

Kushal Patel (M.S. E.C.E., 2021)

Alberto Post (M.S. A.E., 2021)

Mekonen Halefom (M.S. A.E., 2020)

Griffin Hyde (M.S. A.E., 2019)

Meghan Burns (M.S. A.E., 2018)

Sole Advisor

Chang Koo Kang (M.S. A.E., 2017)

Poorva Shukla (M.S. E.S.M., 2017)

Chris Keyorkian (M.S. A.E., 2016)

Sole Advisor

Sole Advisor

Chris Kevorkian (M.S. A.E., 2016)

Tejaswi Gode (M.S. E.E., 2015)

David Allen (M.S. A.E., 2014)

Sole Advisor

Primary Advi

David Allen (M.S. A.E., 2014)

Kevin Antcliff (M.S. A.E., 2014)

Primary Advisor (with Dr. L. McCue-Weil)

Secondary Advisor (with Mr. Mark Guynn)

Jeffrey Garnand-Royo (M.S. A.E., 2013)

Mark Palframan (M.S. A.E., 2013)

Primary Advisor (with Dr. R. Canfield)

Primary Advisor (with Dr. D. Schmale)

Justin Murtha (M.S. A.E., 2009)

Jesse Geisbert (M.S. O.E., 2007)

Chris Schultz (M.S. A.E., 2006)

Amy Linklater (M.S. A.E., 2005)

Michael Morrow (M.S. A.E., 2005)

Chris Nickell (M.S. A.E., 2005)

Sole Advisor

Secondary Advisor (with Dr. J. Black) Primary Advisor (with Dr. C. Sultan) Primary Advisor (with Dr. S. Brizzolara)

Sole Advisor

Sole Advisor

Secondary Advisor (with Dr. M. Patil) Secondary Advisor (with Dr. M. Hajj)

Sole Advisor

Primary Advisor (with Dr. F. Valentinis) Secondary Advisor (with Dr. C. Fuller)

Sole Advisor

Primary Advisor (with Dr. R. McGwier)

Sole Advisor Sole Advisor Sole Advisor

Primary Advisor (with Dr. D. Stilwell) Primary Advisor (with Dr. W. Durham) Primary Advisor (with Dr. E. Cliff)

Secondary Advisor (with Dr. N. Hovakimyan)

Sole Advisor

Sole Advisor

Sole Advisor

Primary Advisor (with Dr. D. Schmale, III) Primary Advisor (with Dr. A. Nayfeh)

Primary Advisor (with Dr. K. Crandall)